# Some More Geometric Data Structures (Windowing cont.)

Computational Geometry – Recitation 12



# Windowing (reminder)

• We have seen how to find axis-aligned lines intersecting an axis-aligned window.



## Interval trees (reminder)

• We have used interval trees:



- In the relevant nodes we searched for the end points contained in a rectangle unbounded from one side.
- For this we have used 2d-Range Trees and then improved to Priority Search Trees.

# Non-Axis-Aligned segments

- What about general segments, that is, not axis-aligned?
  - We will restrict the problem to non-intersecting segments.
- Can we use the solution we already have?
- Use segment bounding box instead!
- Works quite well in practice.
- Worst case is bad:





# Non Axis-Aligned segments

- Can we adopt interval trees?
- The key point in interval trees is knowing that one side of the segment is to the right (or left) of q.
- This doesn't help much if we allow arbitrary orientation.



- Let's remember what interval trees solves in the first place:
- Finding the 1*d*-segments that cover a given point *x*.
- Can we devise another data structure for that?
- If the segments doesn't overlap we can store them in a BST, and looking for the one segment that intersects x is easy.
- But what if they do overlap?



- Given a set S of overlapping segments, we want to find which segments intersects a point x.
- Create a new set, of non overlapping segments and store it in a BST.
  - Add zero-size segments for the end points.
- In each leaf store a list of (original) segments that intersects it.



• We will save these segments in a searching tree



# Segment trees – (space complexity)

- What is the space complexity of this data structure?
- Each segment can appear in many leaves.
- The space complexity is  $O(n^2)$ .
- Can we improve it?
- If a segment appear in consecutive leaves, we can store it in the parent node instead.
- s will be stored in vand  $\mu_5$ .



• The complete data structure:



#### Segment trees (space complexity)

- What is the space complexity now?
- Each segment can appear at most twice at any level of the tree.
- **Proof:** Assume to the contrary:
- All the leaves between  $v_1$  and  $v_3$  contain a segment s.
- Then, all the leaves in the subtree of  $parent(v_2)$ also contain *s*, thus *s* will appear in  $parent(v_2)$ and not in  $v_2$ .
- Conclusion: each segment is stored in O(log n) nodes.
- The space complexity is  $O(n \log n)$ .



- Building a segment tree can also be done in  $O(n \log n)$ .
- How do we find all the segments covering x?
- Search for x in the tree, report all the segment stored in nodes along the search path. (next slide)
- Notice that a segment tree does the same job as a plain interval tree, but with worse space complexity.

**Complexity**:  $O(\log n + k)$ 

- k is the number of reported segments.

#### Segment trees - Query

• The complete data structure:



- So how does segment trees help us?
- Given a set of non-intersecting segments, build a segment tree to their projection on the *x*-axis.
- Using that we can find *potential segments*. Segments that cover the *x* coordinate of the window edge.
- How does this help?



- Each internal node represents the union of segments of its sons.
- A segment will be stored in a node if it covers the whole node-segment.
- This means that the set of segments stored in the node is well ordered.

$$S(v_2) = \{s_1, s_2\}$$

$$v_1$$

$$S(v_1) = \{s_3\}$$

$$v_3$$

$$S(v_3) = \{s_4, s_6\}$$



- The set of segments in each node is well ordered.
  - Intuition: it looks like a (bended) ladder.
- How can we this to find which segments intersect the window edge?
- Store the segments in a BST!



## Segment trees - Complexity

- The space complexity is not affected:  $O(n \log n)$
- The search in each node is done in  $O(\log n)$ , thus, the query complexity is  $O(\log^2 n + k)$
- Building the tree takes  $O(n \log^2 n)$ .
- It can be improved to  $O(n \log n)$  using some tricks.

